

the opacity for each of the subsequent reference signals is calculated (Equation AM1-2). For shot-to-shot consistency, the opacity values shall be within $\pm 3\%$ of 0% opacity and the associated S_o values less than or equal to 8% (full scale) [Section 2.6].

If a set of reference signals fails to meet the requirements of this section, then all plume signals [Section 2.4] from the last set of acceptable reference signals to the failed set shall be discarded.

2.3.1 Initial and Final Reference Signals. Three reference signals shall be obtained within a 90-second time period prior to any data run. A final set of three reference signals shall be obtained within three (3) minutes after the completion of the same data run.

2.3.2 Temporal Criterion for Additional Reference Signals. An additional set of reference signals shall be obtained during a data run if there is a change in wind direction or plume drift of 30° or more from the direction that was prevalent when the last set of reference signals was obtained. An additional set of reference signals shall also be obtained if there is an increase in value of S_{in} (near region standard deviation, Equation AM1-5) or S_{if} (far region standard deviation, Equation AM1-6) that is greater than 6% (full scale) over the respective values calculated from the immediately previous plume signal, and this increase in value remains for 30 seconds or longer. An additional set of reference signals shall also be obtained if there is a change in amplitude in either the near or the far region of the plume signal, that is greater than 6% of the near signal amplitude and this change in amplitude remains for 30 seconds or more.

2.4 Plume Signal Requirements. Once properly aimed, the lidar is placed in operation with the nominal pulse or firing rate of six pulses/minute (1 pulse/10 seconds). The lidar operator shall observe the plume backscatter signals to determine the need for additional reference signals as required by Section 2.3.2. The plume signals are recorded from lidar start to stop and are called a data run. The length of a data run is determined by operator discretion. Short-term stops of the lidar to record additional reference signals do not constitute the end of a data run if plume signals are resumed within 90 seconds after the reference signals have been recorded, and the total stop or interrupt time does not exceed 3 minutes.

2.4.1 Non-hydrated Plumes. The laser shall be aimed at the region of the plume which displays the greatest opacity. The lidar operator must visually verify that the laser is aimed clearly above the source exit structure.

2.4.2 Hydrated Plumes. The lidar will be used to measure the opacity of hydrated or so-called steam plumes. As listed in the ref-

erence method, there are two types, i.e., attached and detached steam plumes.

2.4.2.1 Attached Steam Plumes. When condensed water vapor is present within a plume, lidar opacity measurements shall be made at a point within the residual plume where the condensed water vapor is no longer visible. The laser shall be aimed into the most dense region (region of highest opacity) of the residual plume.

During daylight hours the lidar operator locates the most dense portion of the residual plume visually. During nighttime hours a high-intensity spotlight, night vision scope, or low light level TV, etc., can be used as an aid to locate the residual plume. If visual determination is ineffective, the lidar may be used to locate the most dense region of the residual plume by repeatedly measuring opacity, along the longitudinal axis or center of the plume from the emissions outlet to a point just beyond the steam plume. The lidar operator should also observe color differences and plume reflectivity to ensure that the lidar is aimed completely within the residual plume. If the operator does not obtain a clear indication of the location of the residual plume, this method shall not be used.

Once the region of highest opacity of the residual plume has been located, aiming adjustments shall be made to the laser line-of-sight to correct for the following: movement to the region of highest opacity out of the lidar line-of-sight (away from the laser beam) for more than 15 seconds, expansion of the steam plume (air temperature lowers and/or relative humidity increases) so that it just begins to encroach on the field-of-view of the lidar's optical telescope receiver, or a decrease in the size of the steam plume (air temperature higher and/or relative humidity decreases) so that regions within the residual plume whose opacity is higher than the one being monitored, are present.

2.4.2.2 Detached Steam Plumes. When the water vapor in a hydrated plume condenses and becomes visible at a finite distance from the stack or source emissions outlet, the opacity of the emissions shall be measured in the region of the plume clearly above the emissions outlet and below condensation of the water vapor.

During daylight hours the lidar operators can visually determine if the steam plume is detached from the stack outlet. During nighttime hours a high-intensity spotlight, night vision scope, low light level TV, etc., can be used as an aid in determining if the steam plume is detached. If visual determination is ineffective, the lidar may be used to determine if the steam plume is detached by repeatedly measuring plume opacity from the outlet to the steam plume along the plume's longitudinal axis or center line. The lidar operator should also observe color differences and plume reflectivity to detect a

detached plume. If the operator does not obtain a clear indication of the location of the detached plume, this method shall not be used to make opacity measurements between the outlet and the detached plume.

Once the determination of a detached steam plume has been confirmed, the laser shall be aimed into the region of highest opacity in the plume between the outlet and the formation of the steam plume. Aiming adjustments shall be made to the lidar's line-of-sight within the plume to correct for changes in the location of the most dense region of the plume due to changes in wind direction and speed or if the detached steam plume moves closer to the source outlet encroaching on the most dense region of the plume. If the detached steam plume should move too close to the source outlet for the lidar to make interference-free opacity measurements, this method shall not be used.

2.5 Field Records. In addition to the recording recommendations listed in other sections of this method the following records

should be maintained. Each plume measured should be uniquely identified. The name of the facility, type of facility, emission source type, geographic location of the lidar with respect to the plume, and plume characteristics should be recorded. The date of the test, the time period that a source was monitored, the time (to the nearest second) of each opacity measurement, and the sample interval should also be recorded. The wind speed, wind direction, air temperature, relative humidity, visibility (measured at the lidar's position), and cloud cover should be recorded at the beginning and end of each time period for a given source. A small sketch depicting the location of the laser beam within the plume should be recorded.

If a detached or attached steam plume is present at the emissions source, this fact should be recorded. Figures AM1-I and AM1-II are examples of logbook forms that may be used to record this type of data. Magnetic tape or paper tape may also be used to record data.